

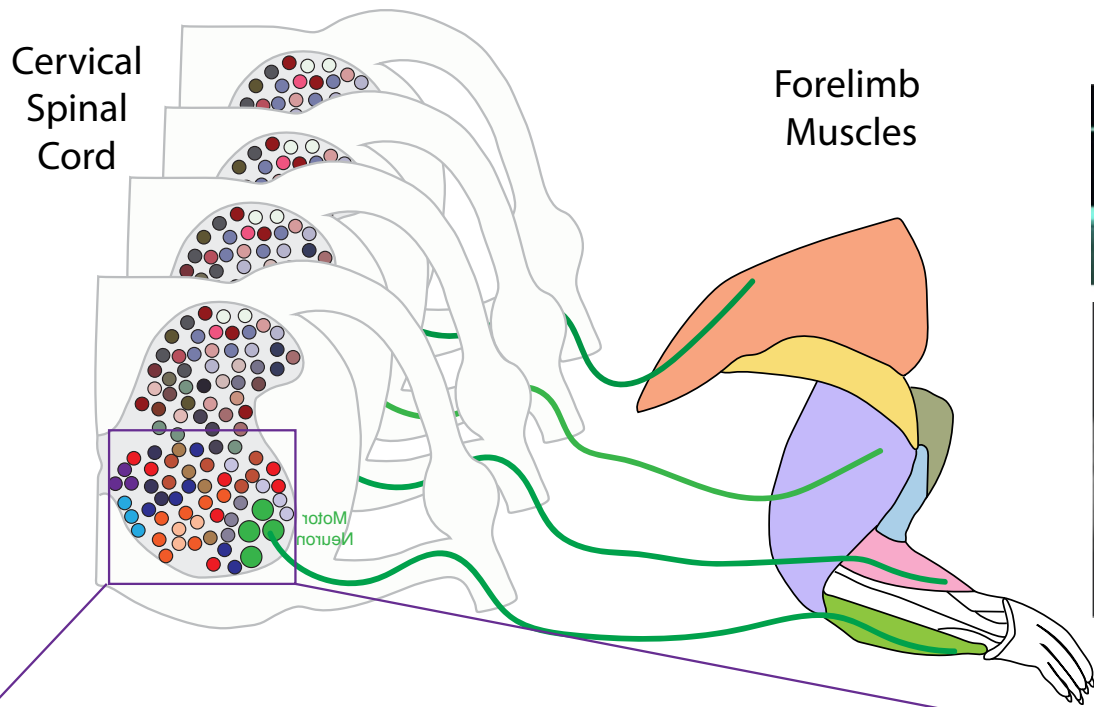
# Spinal Circuits for the Control of Dexterous Movement

NINDS/NIH U19 funded through the BRAIN Initiative

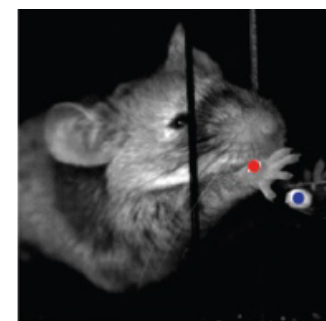
# Spinal Circuits

# Limb Mechanics

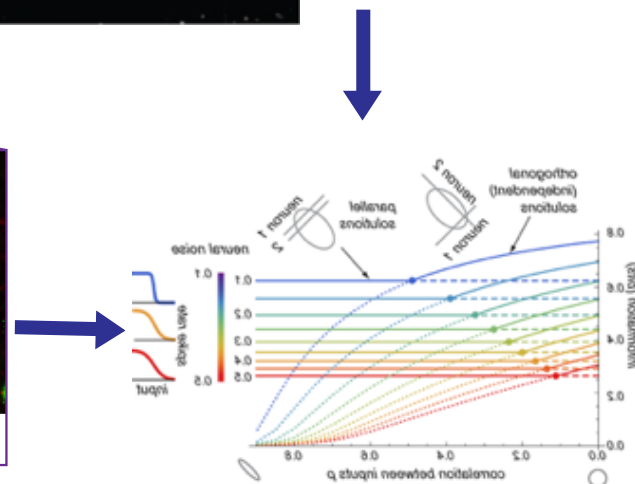
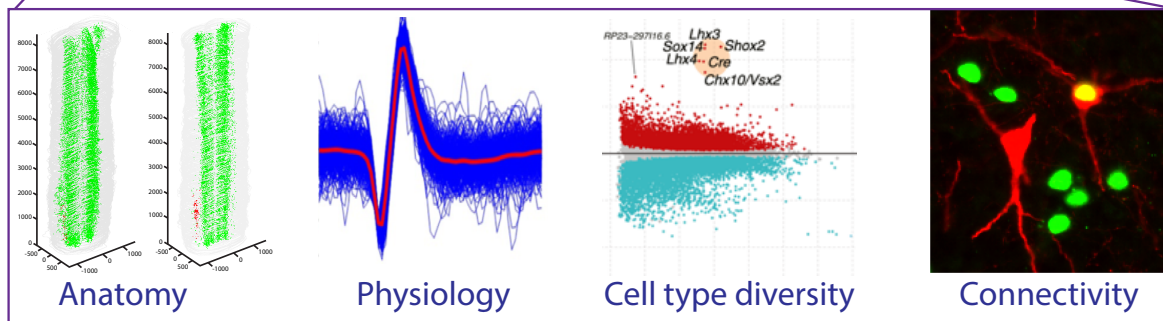
# Behavior



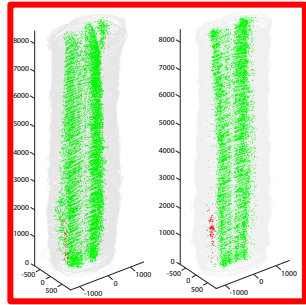
Rhythmic Movement  
Locomotion



Non-Rhythmic  
Movement  
Reaching/Grasping

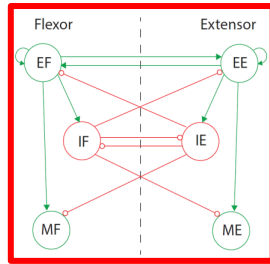


# Modeling

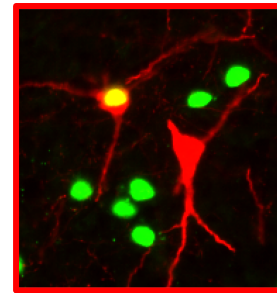
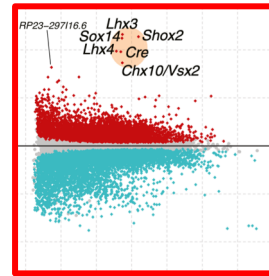


**Anatomy**  
Reference  
Atlas

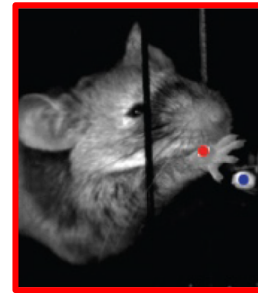
**Modeling**  
Golomb/Sharpee



**Cell Phenotyping**  
Pfaff

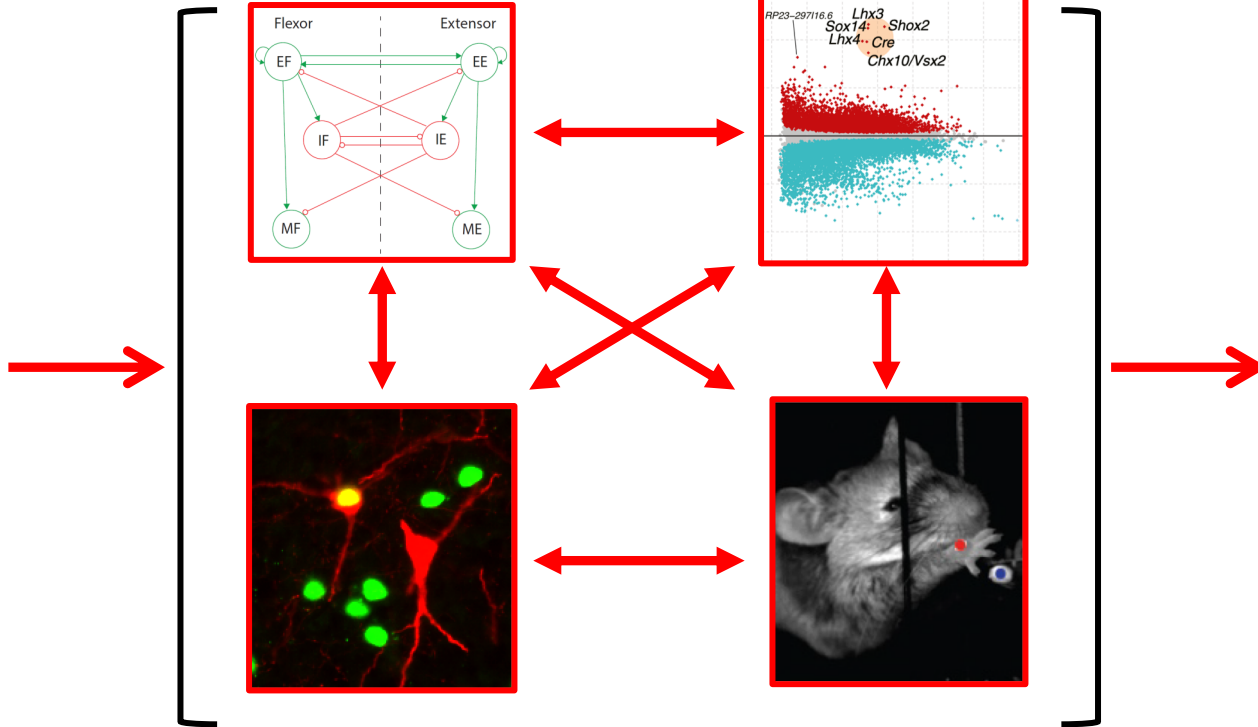


**Connectivity/  
Physiology**  
Goulding

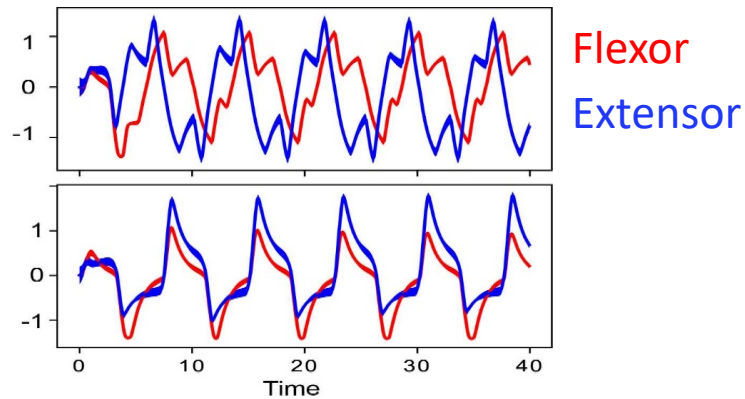


**Behavior/  
In vivo Physiology**  
Azim/Nimmerjahn

**DataCore**  
Sharpee  
MetaCell



## Model motoneuron and muscle recruitment during motor behaviors

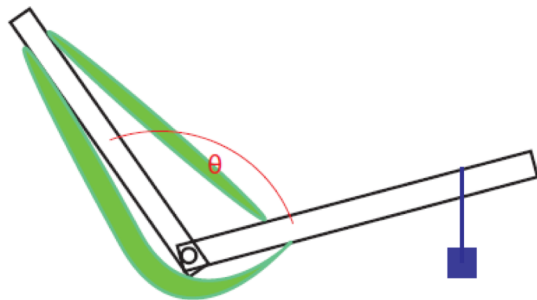


Conductance-based model 
$$C \frac{dV}{dt} = -\sum_{\text{ions}} I_{\text{ions}} - \sum_{\text{syn}} I_{\text{syn}}$$

## Develop models of single neurons and synaptic connections

These models will be incorporated into network models and will be used to evaluate the roles of intrinsic neuronal properties in network dynamics.

## Model mechanical forelimb responses

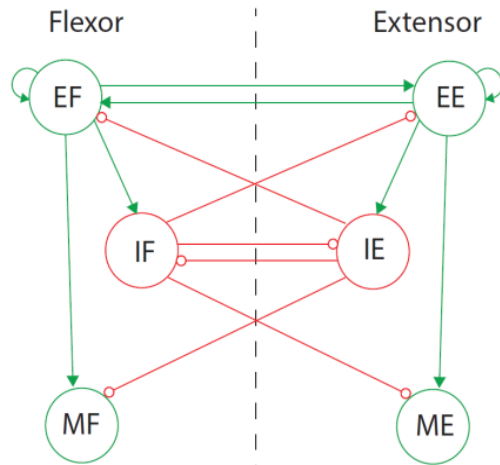


## Constructing simple mechanical models of the elbow and wrist joints

The mechanical models will be combined with the network models to demonstrate how the neuronal circuits control elbow and wrist movements.

Newtonian mechanics, model for muscle contraction

## Model optimal circuit configurations

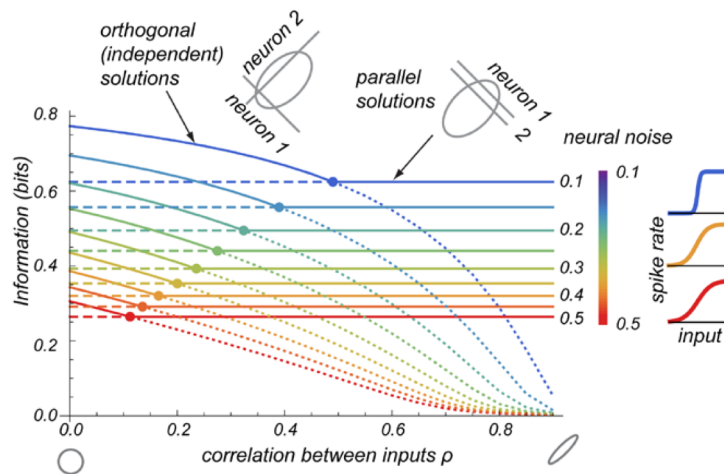


Rate model  $\frac{ds}{dt} = -\frac{s}{\tau_s} M \quad M = \beta \left[ \sum_{\alpha} J_{\alpha} s_{\alpha} - a - \theta \right]_+$

## Building and analyzing models spinal cord circuits

The circuits models account for rhythm generation as well as transition to steady states. Conductance-based models are mapped to rate models that are amenable for analytical treatment.

## Predict cell types

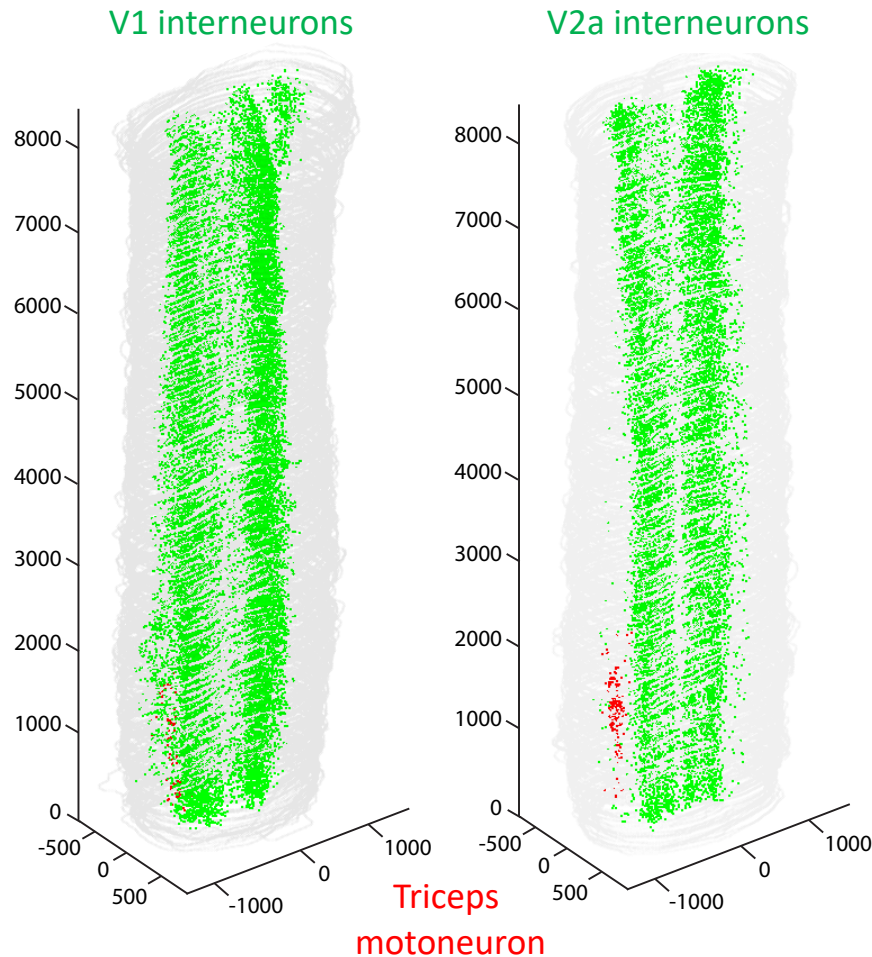


Control theory, Information theory

# Anatomical Scaffold for Modeling and Experimental Studies

## Annotated Atlas of the cardinal premotor interneuron classes

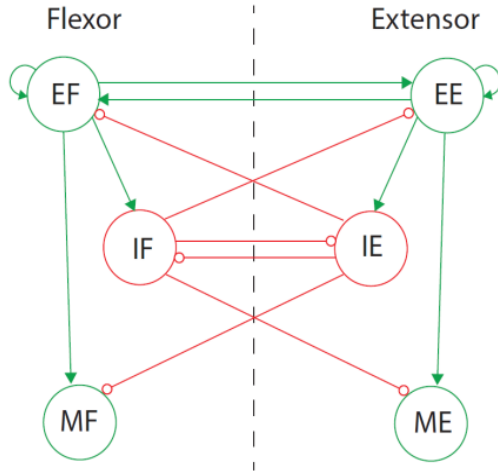
*3D rendering of the spatial distribution of cardinal pre-motor interneurons and reference motoneurons*



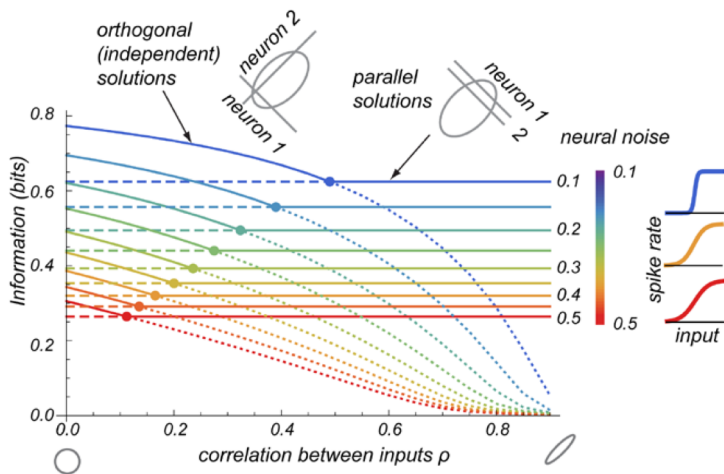
*Spatial distribution plotted with  
Build-a-brain developed by Jeff  
Moore [jemoore@salk.edu](mailto:jemoore@salk.edu)  
3D rendering with Brainmaker and  
Neuroinfo from MBF*

# Modeling Approach

## Model optimal circuit configurations



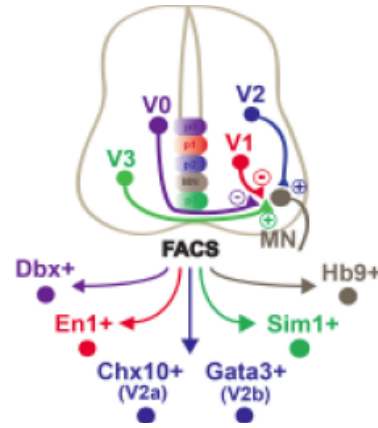
## Predict cell types



# Experimental Approach to Validate Predictions

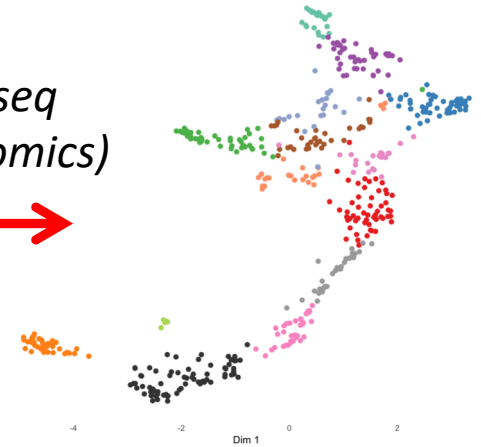
## Molecular Heterogeneity

Embryonic (E13.5)  
Postnatal (P14)  
Adult



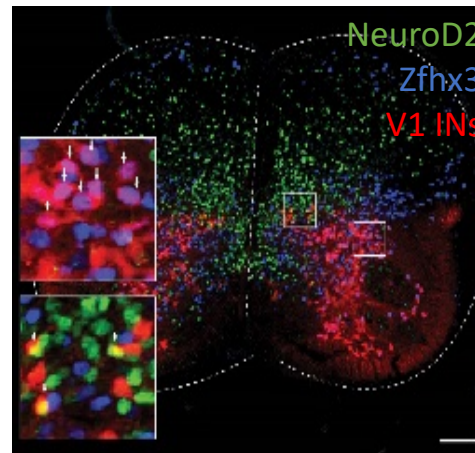
Cluster analysis  
& subtype identification

scRNAseq  
(10x genomics)

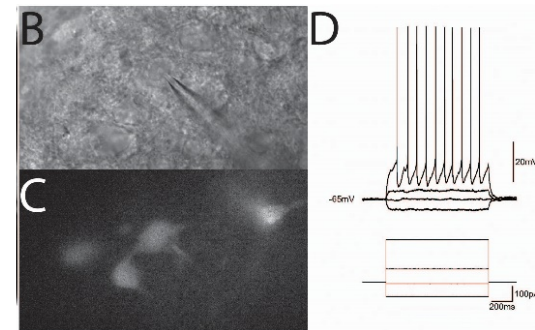


## Subtype validation

Molecular identity

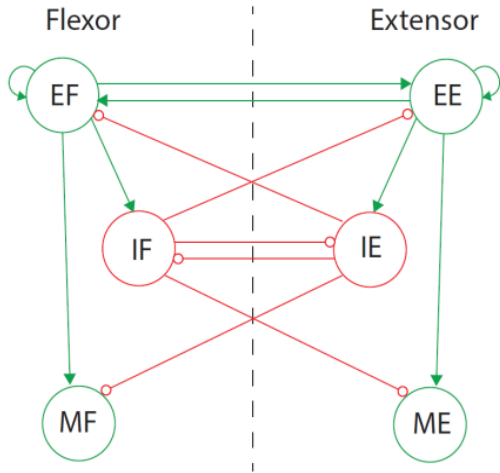


Intrinsic electrophysiological properties



# Modeling Approach

## Model optimal circuit configurations

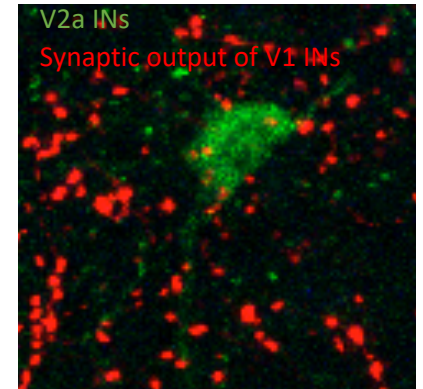
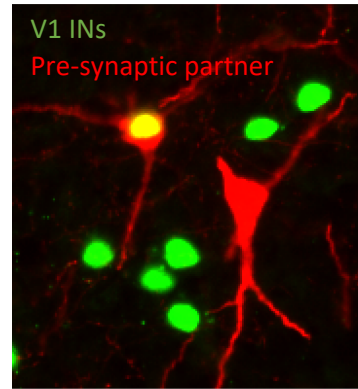


# Experimental Approach to Validate Predictions

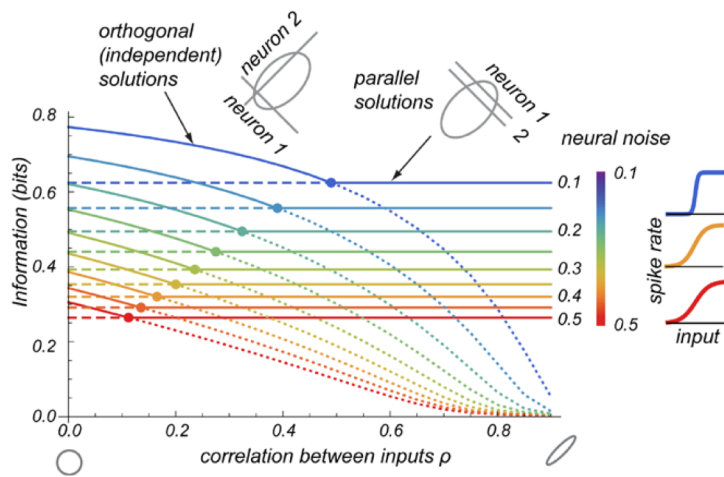
## Anatomical Connectivity

*Rabies tracings for pre-synaptic input*

*Viral tracings for post-synaptic output*



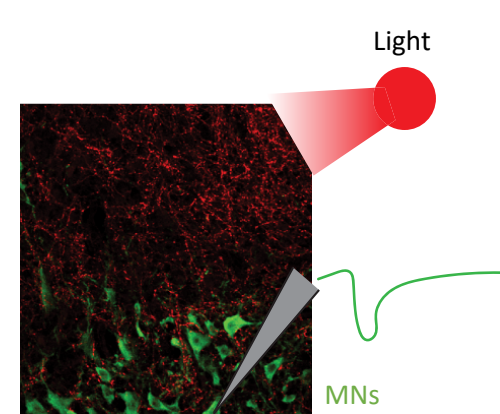
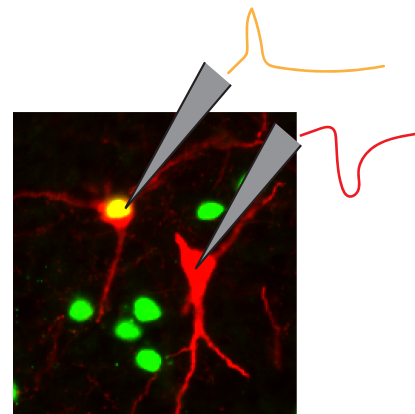
## Predict cell types



## Functional Connectivity

*Paired recordings*

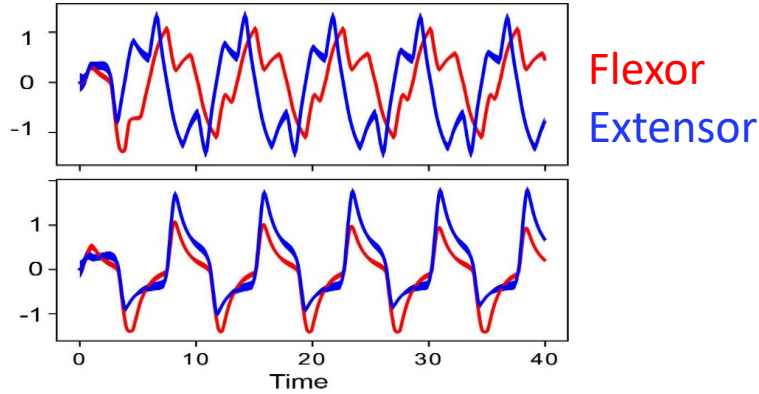
*Optogenetic stimulation*





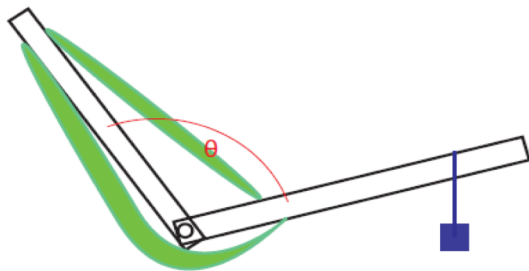
# Modeling Approach

## Model motoneuron and muscle recruitment during motor behaviors



Conductance-based model 
$$C \frac{dV}{dt} = -\sum_{ions} I_{ions} - \sum_{syn} I_{syn}$$

## Model mechanical forelimb responses

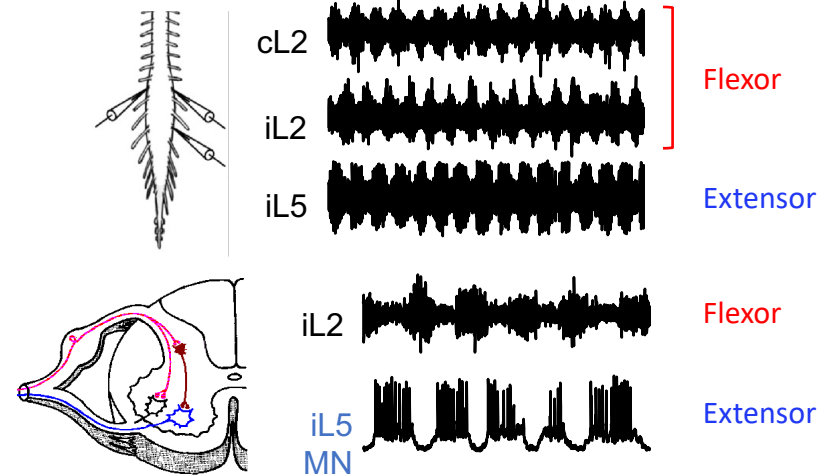


Newtonian mechanics, model for muscle contraction

# Experimental Approach to Validate Predictions

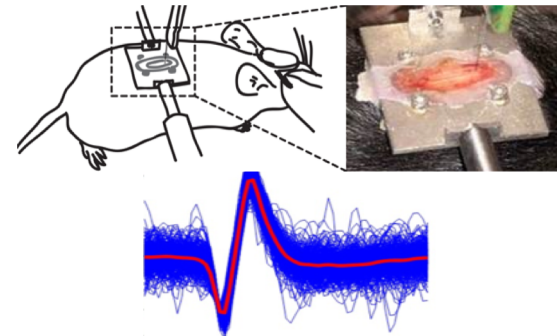
## In vitro recordings

Measure changes in motoneuron currents upon modulating the activity of the cardinal pre-motor interneuron classes



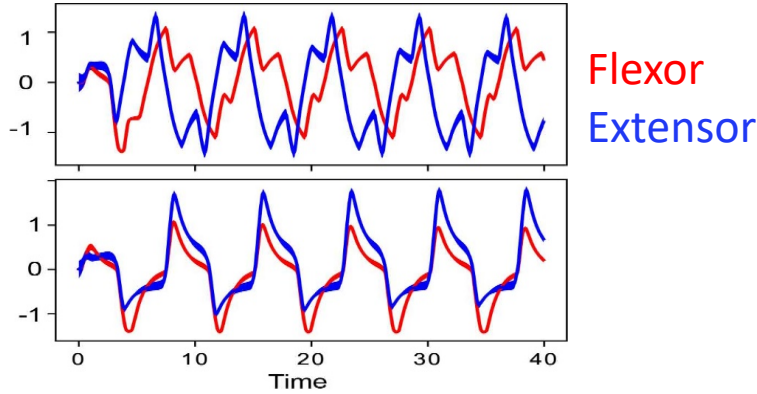
## In vivo spinal neuron recordings

Analyze the firing pattern of the cardinal pre-motor interneuron classes using opto-tagging in behaving mice



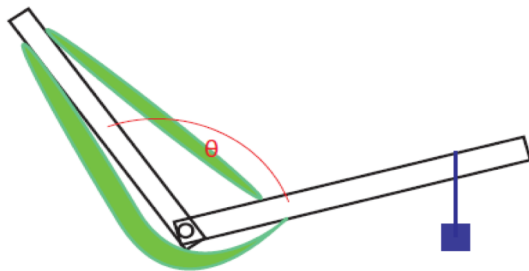
# Modeling Approach

Model motoneuron and muscle recruitment during motor behaviors



Conductance-based model  $C \frac{dV}{dt} = -\sum_{ions} I_{ions} - \sum_{syn} I_{syn}$

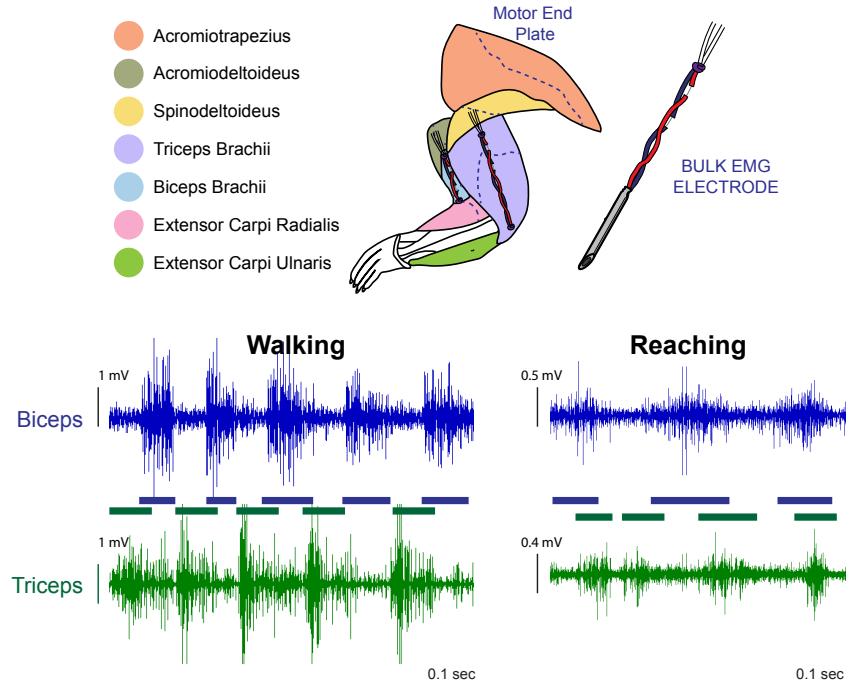
Model mechanical forelimb responses



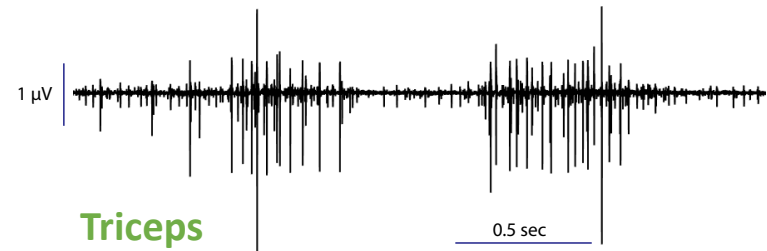
Newtonian mechanics, model for muscle contraction

# Experimental Approach to Validate Predictions

Bulk EMG Recordings in freely moving mice

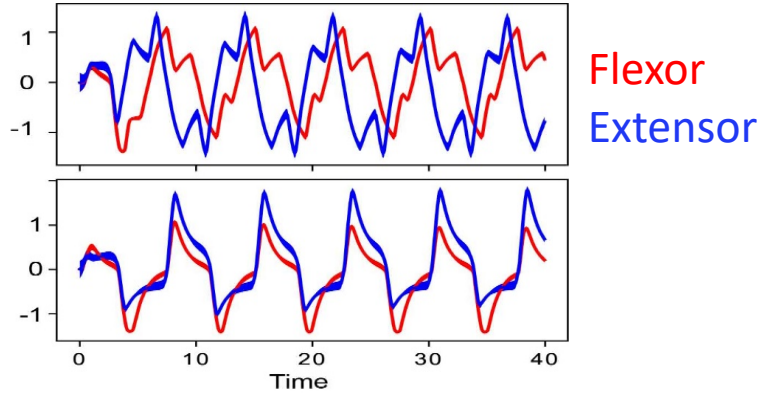


Single Motor Unit EMG Recordings



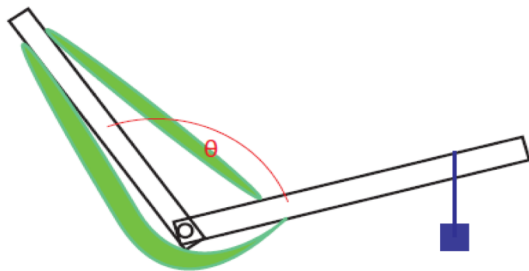
# Modeling Approach

Model motoneuron and muscle recruitment during motor behaviors



Conductance-based model  $C \frac{dV}{dt} = -\sum_{ions} I_{ions} - \sum_{syn} I_{syn}$

Model mechanical forelimb responses

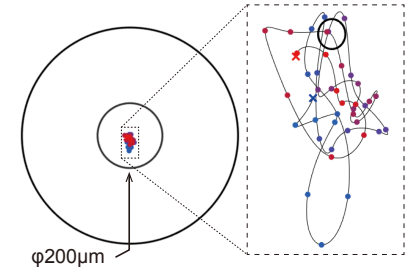
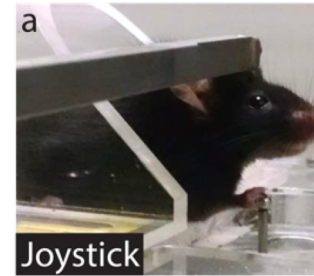


Newtonian mechanics, model for muscle contraction

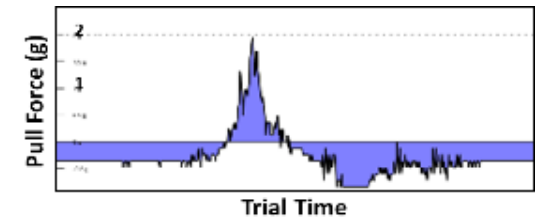
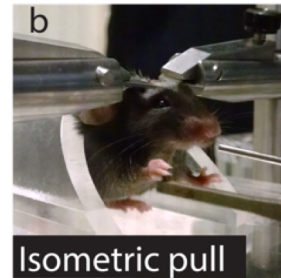
# Experimental Approach to Validate Predictions

Measure motor behavior changes upon perturbing the function of the cardinal premotor interneuron classes

*Elbow flexion/extension*



*Elbow isometric contraction*



*Wrist abduction/adduction*

