

**Virtual Surgery** 

#### Suvranu De

J. Erik Jonsson '22 Distinguished Professor of Engineering
Director, Center for Modeling, Simulation and Imaging in Medicine (CeMSIM)
Head, Department of Mechanical, Aerospace and Nuclear Engineering
Rensselaer Polytechnic Institute, Troy, NY



#### No disclosures



#### Research Collaborative why not change the world?

#### **Collaborating Hospitals:**

Beth Israel Deaconess Medical Center (MA) Massachusetts General Hospital (MA) Cambridge Health Alliance (MA) Mount Auburn Hospital (MA) Tufts University (MA) Yale University Medical School (CT) University at Buffalo (NY) Baylor University Medical Center (TX) University of Texas Southwestern Medical

#### Academic Collaborators:

Harvard Medical School University at Buffalo Wright State University University of Central Arkansas

#### Industrial Partners:

Kitware Simquest **CFDRC** Infocitex Charles River Analytics



Center (TX)





University of Texas San Antonio (TX)



















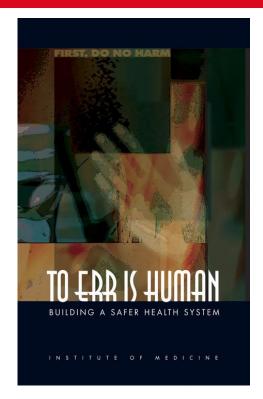






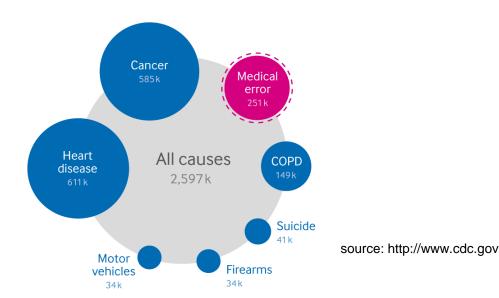


#### To Err is Human



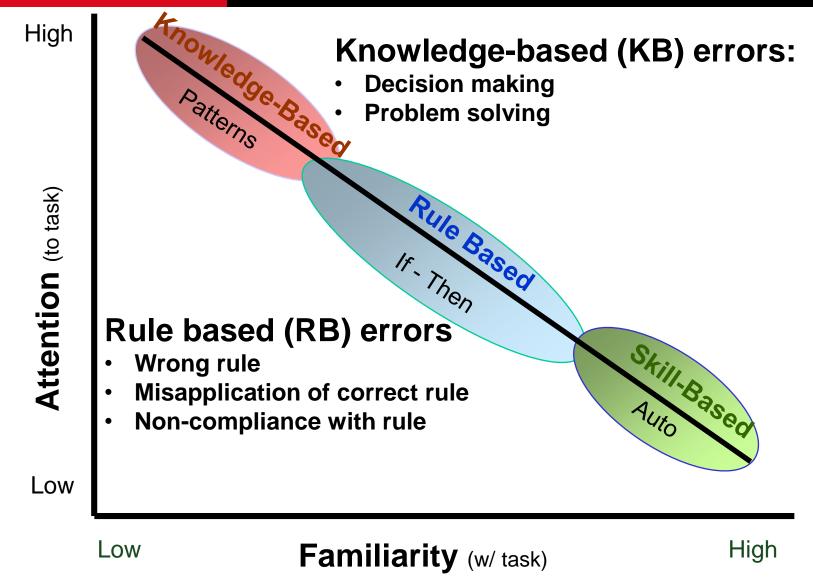
98,000 Americans die per year of medical errors [Institute of Medicine, 1999]

Causes of death in the US, 2013





## Nature of Human Error why not change the world?



Rasmussen's Skill-Rule-Knowledge (SRK) Framework



## Residency Model

#### "See one, do one, teach one"



Challenges of the residency model:

Patient safety
Complex cases
High cost ~ \$50K/year/trainee
Subjective assessment
Reduced patient contact

- 80 hour work week
- Increased malpractice liability
- Reduced hospital stays

## Rensselaer Human Safety Background Chot change the world?

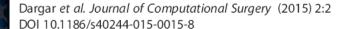
#### The Human Safety Framework

- Individual patient/operator/user
- Provider
- Tools, Smart instrumentation
- Team
- System
- **Population**
- Disease level/injury level
- Data and information sharing

# Virtual Surgery

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Journal of Computational Surgery
 a SpringerOpen Journal

REVIEW Open Access

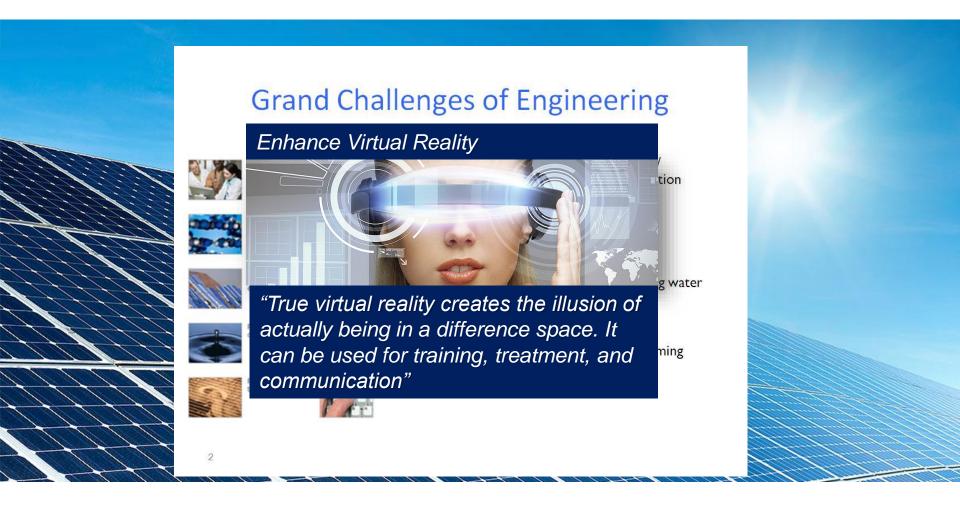
Towards immersive virtual reality (iVR): a route to surgical expertise

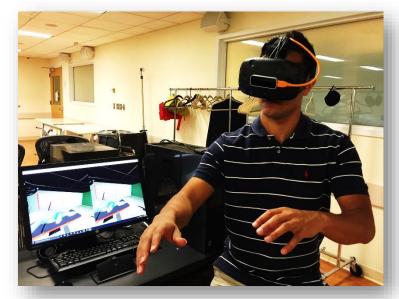
Saurabh Dargar, Rebecca Kennedy, WeiXuan Lai, Venkata Arikatla and Suvranu De\*

- High fidelity
- Risk-free
- Rare conditions
- Objective evaluation

## Virtual Lap-Band







#### Interactivity

Technical Challenges

Real time graphics (min 30 frames/sec)

Real-time haptics (min 1000 frames/sec)

## **High fidelity**

Multi-physics

Multi-phase

Multi-scale

# Thank you!



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